$EQ-30_{\text{SERIES}}$

Adjustable Long Range & Fixed-focus Reflective Photoelectric Sensor Amplifier Built-in



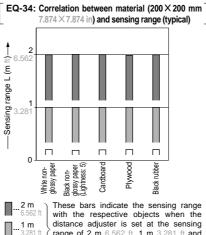
Unaffected by color or material, 2 m (6.562 ft) distance adjustable fixed-focus sensing



Not affected by object color or background

As the EQ-30 series is incorporated with a 2-segment photodiode as the receiving element with a unique circuitry, it detects an object at the same distance regardless of its color or the background beyond the adjusted sensing range.

However, when the background is specular, it may be necessary to change the angle of the sensor.



distance adjuster is set at the sensing range of 2 m 6.562 ft, 1 m 3.281 ft and ...1 m 3.281 ft 0.2 m 0.656 ft long, each, with white non-0.2 m glossy paper.

It saves space, since a miniaturized

housing of W20 imes H68 imes D40 mm

W0.787 × H2.677 × D1.575 in has

been designed for the fixed-focus

sensing sensor even though the

adjustable sensing range is 2 m 6.562 ft

40 mm 1 579 ➤ 20 mm 0.787 in

Compact

long.

These bars indicate the sensing range with the respective objects when the

line, etc.

Long sensing range 2 m 6.562 ft

The EQ-30 series can detect an object

It is suitable for various applications,

such as, sensing objects or positioning

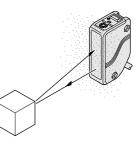
objects traveling on a wide assembly

2 m 6.562 ft away.

2 m 562 ft

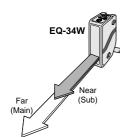
Insusceptible to contamination on lens

The fixed-focus sensing keeps the detectability better than diffuse reflective type sensors even if the lens is contaminated by dirt, dust, mist, or smoke under an unclean environment.



Two distances (far and near) can be set EQ-34W

With EQ-34W, two sensing distances, Far (Main) and Near (Sub), can be set. Hence, one sensor can suffice where, earlier, two were required.



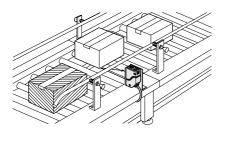
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PHOTOELECTRIC SENSOR

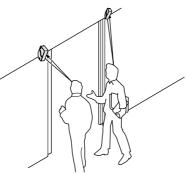
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APPLICATIONS

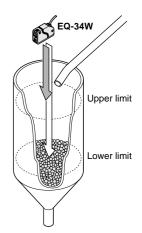
Detecting traveling cardboard boxes



Detecting people in front of automatic door



Detecting level in hopper



Automatic interference prevention

The EQ-30 series is the first fixedfocus sensing reflective type sensor to incorporate an automatic interference prevention function so that two sets of sensors can be installed close together or facing each other.

Mechanical 2-turn adjuster with indicator

It features a mechanical 2-turn distance adjuster with an indicator that shows the set distance at a glance.

/Distance adjuster (2-turn)

Normal reflective type sensors

operate by sensing the variation in

the amount of incident beam.

However, the fixed-focus reflective

sensing type sensor incorporating the 2-segment photodiode operates by sensing the variation in the incident beam angle. Thus, the output is

activated according to the distance of

This system helps the EQ-30 series in

being unaffected by object color or a

background, enabling stable sensing.

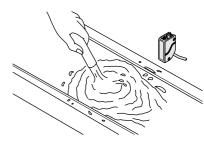
the object from the sensor.

Principle of fixed-focus sensing with 2-segment photodiode

Adjuster indi

Waterproof

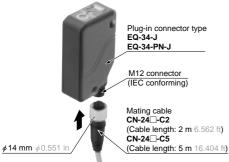
It has IP67 protection. It can be used in places splashed with water.



Note: However, take care that if it is exposed to water splashes during operation, it may detect a water drop itself.

Plug-in connector type is available

Plug-in connector type, which can be easily disconnected for replacement is available. In case a problem occurs, anyone can replace the sensor in a minute. (Excluding EQ-34W)



Plug-in connector type EQ-34-J

(Cable length: 2 m 6.562 ft)

2-segment photodiode Emitting LED

Sensing is based on the difference in the incident beam angle of the dotted line and the solid line in the above figure.

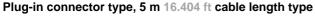
Amplifier Built-in

ORDER GUIDE

Туре	Appearance	Adjustable range (Note)	Model No.	Output
NPN output			EQ-34	NPN open-collector transistor
PNP output		0.2 to 2 m 0.656 to 6.562 ft	EQ-34-PN	PNP open-collector transistor
Two outputs			EQ-34W	Two NPN open-collector transistor outputs

NOTE: Mounting bracket is not supplied with the sensor. Please select from the range of optional sensor mounting brackets (two types).

Note: The adjustable range stands for the maximum sensing range which can be set with the adjuster. The sensor can detect an object 0.1 m 0.328 ft, or more, away. However, the detectable range of Near (Sub) type of **EQ-34W** begins at 0.2 m 0.656 ft.



Plug-in connector type (standard: cable type) and 5 m 16.404 ft cable length type (standard: 2 m 6.562 ft) are also available.

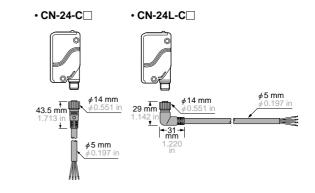
Table of Model Nos.

Туре	Standard	Plug-in connector type (Note)	5 m 16.404 ft cable length type
NPN output	EQ-34	EQ-34-J	EQ-34-C5
PNP output	EQ-34-PN	EQ-34-PN-J	
Two outputs	EQ-34W		EQ-34W-C5

Note: Please order the suitable mating cable separately.

Mating cable for plug-in connector type

Туре	Model No.	Description		
Straight	CN-24-C2	Length: 2 m 6.562 ft	0.34 mm ² 4-core cabtyre cable with connector on one end Cable outer diameter:	
Straight	CN-24-C5	Length: 5 m 16.404 ft		
Elbow	CN-24L-C2	Length: 2 m 6.562 ft		
EIDOW	CN-24L-C5	Length: 5 m 16.404 ft		



Non-detectable

range

0.1 m

Actual sensing range of the sensor

0.2 m 0.656 ft Adjustable range 2 m 6.562 ft

> Sensing object

OPTIONS

Designation	Model No.	Description
Sensor	MS-EQ3-1	Back angled mounting bracket
mounting bracket	MS-EQ3-2	Foot angled mounting bracket

Note: The plug-in connector type does not allow use of some sensor mounting brackets because of the protrusion of the connector.

Sensor mounting bracket

• MS-EQ3-1 Two M4 (length 25 mm 0.984 in) screws with washers and two M4 nuts are attached.

84 in) Prs re

• MS-EQ3-2

Two M4 (length 25 mm 0.984 in) screws with washers and two M4 nuts are attached.

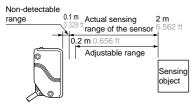


SPECIFICATIONS

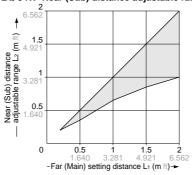
\sim		Туре	NPN output	PNP output	Two outputs	
ltem		Model No.	EQ-34	EQ-34-PN	EQ-34W	
Adjustable range (Note 1)		(Note 1)	0.2 to 2 m 0.6	556 to 6.562 ft	Far (Main): 0.2 to 2 m 0.656 to 6.562 ft Near (Sub): Refer to diagram in (Note 2)	
Sensing range (with white non-glossy paper (at setting distance 2 m 6.562 ft)			0.1 to 2 m 0.3	328 to 6.562 ft	Far (Main): 0.1 to 2 m 0.328 to 6.562 ft Near (Sub): 0.2 to 2 m 0.656 to 6.562 ft [with Near (Sub) distance for adjuster at max.]	
Hyster	esis			10 % or less of operation distance	1	
Repea	atability		Along sensing axis: 10 mm 0.394 in or les	s, Perpendicular to sensing axis: 1 mm 0.0	39 in or less (with white non-glossy paper)	
Supply	voltage			10 to 30 V DC Ripple P-P 10 % or less		
Currer	nt consump	tion	50 mA or less	55 mA or less	90 mA or less	
Output	t		NPN open-collector transistor • Maximum sink current: 100 mA • Applied voltage: 30 V DC or less (between output and 0 V) • Residual voltage: 1 V or less (at 100 mA sink current) 0.4 V or less (at 16 mA sink current)	PNP open-collector transistor • Maximum source current: 100 mA • Applied voltage: 30 V DC or less (between output and + V) • Residual voltage: 1 V or less (at 100 mA source current) 0.4 V or less (at16 mA source current)	between Near (Sub) output and 0 V • Residual voltage: 1 V or less (at 100 mA sink current)	
U	tilization ca	tegory		DC-12 or DC-13	· · · · · · · · · · · · · · · · · · ·	
	utput opera		Sw	itchable either Detection-ON or Detection-O	OFF	
	hort-circuit		Incorporated			
Respo	onse time		2 ms or less			
Operation indicator		or	Red LED (lights up when the output is ON)		Far (Main) output: Red LED [lights up when the Far [(Main) output is ON] Near (Sub) output: Red LED [lights up when the Near [Sub) output is ON	
Stabili	ty indicator		Green LED (lights up un	der stable light received condition or stable	e dark condition) (Note 3)	
Distance adjuster			2-turn mechanical adjuster with pointer		Far (Main): 2-turn mechanical adjuster with pointer Near (Sub): Variable adjuster	
Automati	ic interference p	prevention function	Incorporated (Two units of sensors can be mounted close together.)			
P	ollution deg	ree	3 (Industrial environment)			
_e Pi	rotection			IP67 (IEC)		
	mbient tem	perature	- 20 to + 55 °C - 4 to + 131 °F (No dew condensation or icing allowed), Storage: - 25 to + 70 °C - 13 to + 158 °F			
	mbient hum	nidity	35 to 85 % RH, Storage: 35 to 85 % RH			
	mbient illun	ninance	Sunlight: 10,000 ℓ x at the light-receiving face, Incandescent light: 3,000 ℓ x at the light-receiving face			
EI	MC		EN 50081-2, EN 50082-2, EN 60947-5-2			
Environmental resistance	oltage withs	standability	1,000 V AC for one min. between all supply terminals connected together and enclosure			
<u>ا</u> م	sulation res		20 M Ω , or more, with 250 V megger between all supply terminals connected together and enclosure			
^{II} Vi	ibration res	istance	10 to 55 Hz frequency, 1.5 mm 0.059 in amplitude (10 G max.) in X, Y and Z directions for two hours each			
S	hock resista	ance	500 m/s ² acceleration (50 G approx.) in X, Y and Z directions for three times each			
Emitting element			Infrared LED (modulated)			
/lateri	al		Enclosure: Polyalylate and Polyethylene terephthalate, Lens: Polyalylate			
Cable			0.3 mm ² 3-core (EQ-34W: 4-core) cabtyre cable, 2 m 6.562 ft long			
Cable extension			Extension up to total 100 m 328.084 ft is possible with 0.3 mm ² , or more, cable.			
Cable	Weight		150 g approx.			
				Adjusting screwdriver: 1pc.		

Notes: 1) The adjustable range stands for the maximum sensing range which can be set with the adjuster.

The sensor can detect an object 0.1 m 0.328 ft, or more, away. However, the detectable area of the Near (Sub) type of the **EQ-34W** begins at 0.2 m 0.656 ft.





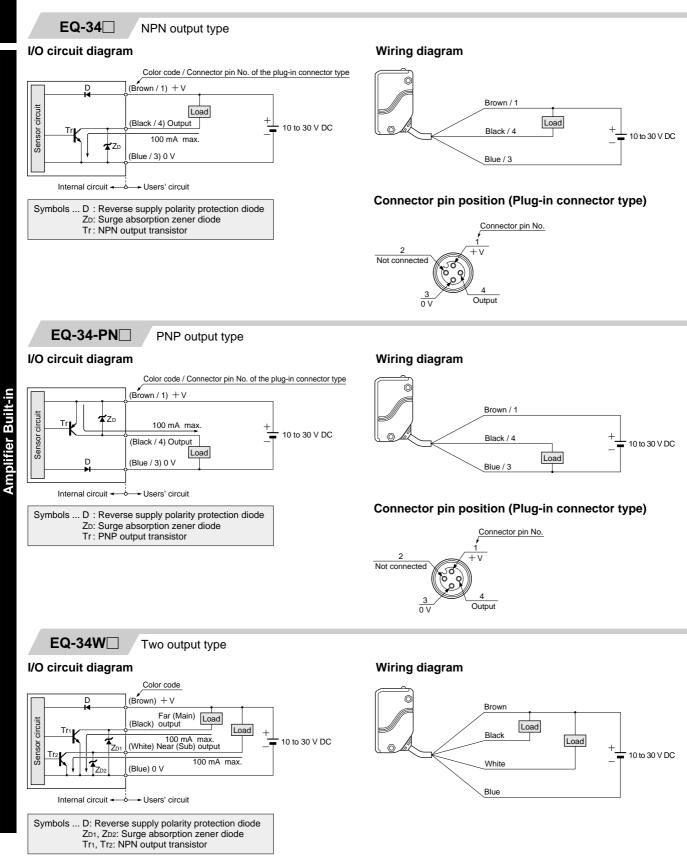


Far (Main) setting	Near (Sub) distance	
distance L1	Near (Sub) distance adjustable range L ₂	
2 m 6.562 ft	1 to 2 m 3.281 to 6.562 ft	
1.5 m 4.921 ft	0.85 to 1.5 m 2.789 to 4.921 ft	
1 m 3.281 ft	0.65 to 1 m 2.133 to 3.281 ft	
0.5 m 1.640 ft	0.35 to 0.5 m 1.148 to 1.640 ft	
0.2 m 0.656 ft	0.2 m 0.656 ft	
1 m 3.281 ft 0.5 m 1.640 ft	0.65 to 1 m 2.133 0.35 to 0.5 m 1.148	

CX-4

3) Refer to 'PRECAUTIONS FOR PROPER USE' on p.262 for the details of the stability indicator.

I/O CIRCUIT AND WIRING DIAGRAMS



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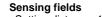
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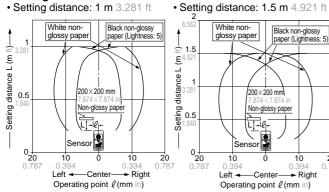
EQ-30

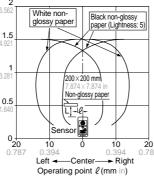
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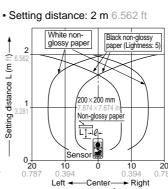
SENSING CHARACTERISTICS (TYPICAL)

EQ-34 EQ-34-PN



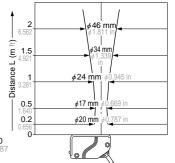






Operating point ℓ (mm in)

Emitted beam

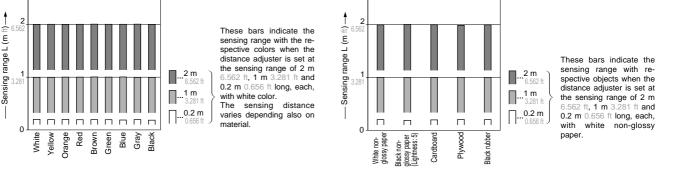


Correlation between color (200 × 200 mm 7.874 × 7.874 in non-glossy paper) and sensing range Correlation between material (200 × 200 mm 7.874 × 7.874 in) and sensing range

L (m ft)

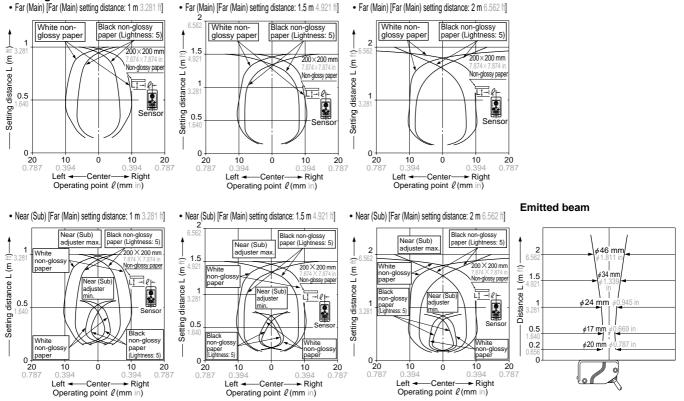
distance

Setting '



EQ-34W

Sensing fields



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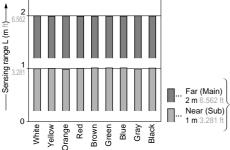
PHOTOELECTRIC SENSORS

EQ-30

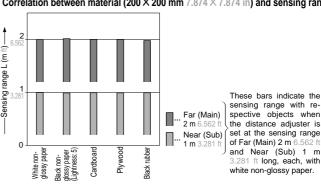
SENSING CHARACTERISTICS (TYPICAL)

EQ-34W

Correlation between color (200 × 200 mm 7.874 × 7.874 in non-glossy paper) and sensing range Correlation between material (200 × 200 mm 7.874 × 7.874 in) and sensing range



These bars indicate the sensing range with respective colors when the distance adjuster is set at the sensing range of Far (Main) 2 m 6.562 ft and Near (Sub) 1 m 3.281 ft long, each, with white color. The sensing distance varies depending also on material.



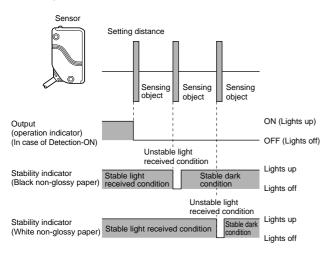
PRECAUTIONS FOR PROPER USE

This product is not a safety sensor. Its use is not intended or designed to protect life and prevent body injury or property damage from dangerous parts of machinery. It is a normal object detection sensor.

Stability indicator

• Since the **EQ-30** series uses a 2-segment photodiode as its receiving element, and sensing is done based on the difference in the incident beam angle of the reflected beam from the sensing object, the output and the operation indicator operate according to the object distance.

Further, the stability indicator shows the margin of the incident light intensity and not that of the object distance. Hence, the distance at which it lights up/off depends on the object reflectivity and is not at all related to the output operation. Do not use the sensor when the stability indicator is off (unstable light received condition), since the sensing will be unstable.

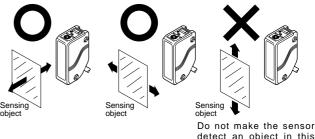


Others

- Do not use during the initial transient time (50 ms) after the power supply is switched on.
- When connecting the mating cable to the plug-in connector type, the tightening torque should be 0.4N·m or less.

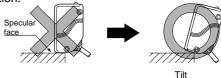
Refer to $p.1135 \sim$ for general precautions.

- Care must be taken regarding the sensor mounting direction with respect to the object's direction of movement.



Do not make the sensor detect an object in this direction because it may cause unstable operation.

- When detecting a specular object (aluminum or copper foil) or an object having a glossy surface or coating, please take care that there are cases when the object may not be detected due to a small change in angle, wrinkles on the object surface, etc.
- When a specular body is present below the sensor, use the sensor by tilting it slightly upwards to avoid wrong operation.



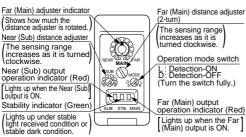
- If a specular body is present in the background, wrong operation may be caused due to a small change in the angle of the background body. In that case, install the sensor at an inclination and confirm the operation with the actual sensing object.
- Take care that some objects may produce a dead zone right in front of the sensor.

PRECAUTIONS FOR PROPER USE

Distance adjustment

EQ-34W

<Adjusters>



<Adjusting procedure> Far (Main)

•	~	(main)	

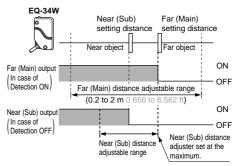
Step	Description	Distance adjuster
1	Turn the Far (Main) distance adjuster fully counterclockwise to the minimum sensing point of 0.2 m 0.656 ft approx.	NEAR GOST FAR MAIN Turn fully
2	Place an object at the far place at the required distance from the sensor, turn the Far (Main) distance adjuster gradually clockwise, and find out point (A) where the sensor changes to the light received condition.	NEAR OF SP FAR MAIN
3	Remove the object, turn the Far (Main) distance adjuster further clockwise, and find out point (B) where the sensor changes to the light received condition again with only the background. / When the sensor does not go to the light received condition even if the adjuster is fully turned clockwise, point (B) is this extreme point in the range.	
4	The optimum position to stably detect objects for the Far (Main) setting is the center point between $(\widehat{\mathbb{A}})$ and $(\widehat{\mathbb{B}})$.	A Optimum NEAR CG 35 FAR MAIN B

Near (Sub)

Step	Description	Distance adjuster
5	Turn the Near (Sub) distance adjuster fully counterclockwise to the minimum sensing point.	SUB Control Sub Control Sub Turn fully
6	Place an object at the near position, at the required distance from the sensor, turn the Near (Sub) distance adjuster gradually clockwise, and find out point \textcircled{C} where the sensor changes to the light received condition.	SUB C C C C C C C C C C C C C C C C C C C
0	Remove the object from the near position, and place the object for Far (Main) sensing at the sensing position. Turn the Near (Sub) distance adjuster further clockwise, and find out point ()) where the sensor changes to the light received condition again with only the background. When the sensor does not go to the light received condition even if the adjuster is fully turned clockwise, point () is this extreme point.	
8	The optimum position to stably detect objects for the Near (Sub) setting is the center point between \bigcirc and \bigcirc .	SUB Optimum Position

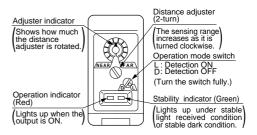
Refer to p.1135~ for general precautions.

- Notes: 1) Turn the distance adjuster gradually and lightly with the attached screwdriver.
 - If the distance adjuster is over turned or pressed heavily, it may be damaged.
 - 2) The Far (Main) distance adjustment should be done before the Near (Sub) distance adjustment. Take care that the Near (Sub) setting distance changes with change in the Far (Main) setting distance.



EQ-34, EQ-34-PN

<Adjusters>



<Adjusting procedure>

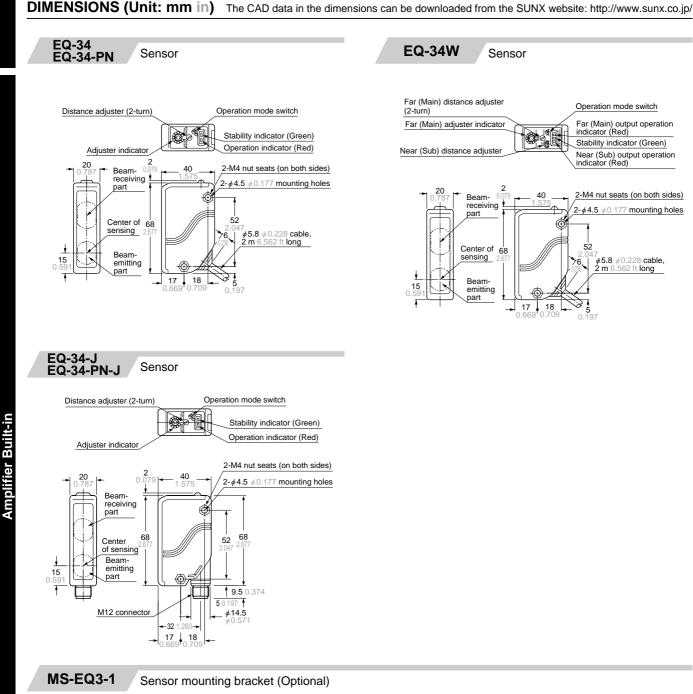
Step	Description	Distance adjuster
1	Turn the distance adjuster fully counterclockwise to the minimum sensing range position of 0.2 m 0.656 ft approx.	Turn fully
2	Place an object at the required distance from the sensor, turn the distance adjuster gradually clockwise, and find out point (a) where the sensor changes to the light received condition.	NEAR FAR
3	Remove the object, turn the distance adjuster further counterclockwise, and find out point (B) where the sensor changes to the light received condition again with only the background. (When the sensor does not go to the light received condition even if the adjuster is fully turned clockwise, point (B) is this extreme point in the range.	A FAR B
4	The optimum position to stably detect objects is the center point between (Å) and (B).	NEAR EAR B

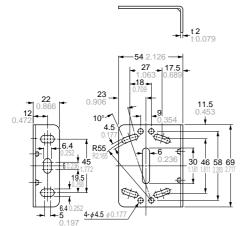
Note: Turn the distance adjuster gradually and lightly with the attached screwdriver.

If the distance adjuster is over turned or pressed heavily, it may be damaged.

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EQ-30

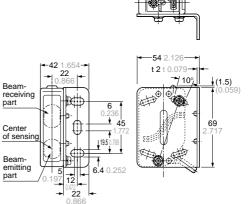




Material: Cold rolled carbon steel (SPCC) Two M4 (length 25 mm 0.984 in) screws with washers and two M4 nuts are attached.

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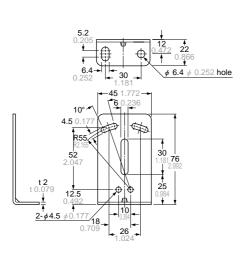
Assembly dimensions Mounting drawing with EQ-34



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DIMENSIONS (Unit: mm in) The CAD data in the dimensions can be downloaded from the SUNX website: http://www.sunx.co.jp/

MS-EQ3-2 Sensor mounting bracket (Optional)



Material: Cold rolled carbon steel (SPCC) Two M4 (length 25 mm 0.984 in) screws with washers and two M4 nuts are attached. Assembly dimensions Mounting drawing with EQ-34

